Algebraic methods for the study of biochemical reaction networks

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NSF/CBMS Conference - David Cox, TCU, 2018

1 Chemical reaction networks and our main goal

- 2 Multistationarity and persistence
- **3** Some important biological netwoks
- 4 MESSI Systems
- 5 OTHER APPROACHES TO MULTISTATIONARITY
- 6 CONCLUSIONS

Two-component signal transduction systems enable bacteria to sense, respond, and adapt to a wide range of environments, stressors, and growth conditions. It relies on phosphotransfer reactions.

$$\begin{array}{ccc} HK_{00} & \xrightarrow{k_1} HK_{p0} & \xrightarrow{k_2} HK_{0p} & \xrightarrow{k_3} HK_{pp} \\ \\ HK_{0p} + RR & \xrightarrow{k_4} HK_{00} + RR_p \\ \\ HK_{pp} + RR & \xrightarrow{k_5} HK_{p0} + RR_p \\ \\ \\ RR_p & \xrightarrow{k_6} RR, \end{array}$$

 $k = (k_1, \ldots, k_6)$ are positive rate constants.

The hybrid histidine kinase HK has two phosphorylable domains: the four possible states of HK are HK_{00} , HK_{P0} , HK_{0P} , HK_{PP} . RR is the unphosphorylated response regulator protein, RR_P the phosphorylated form.

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Call x_1, \ldots, x_6 the concentration of the species of the network:

$$X_{1} \xrightarrow{k_{1}} X_{2} \xrightarrow{k_{2}} X_{3} \xrightarrow{k_{3}} X_{4}$$

$$X_{3} + X_{5} \xrightarrow{k_{4}} X_{1} + X_{6}$$

$$X_{4} + X_{5} \xrightarrow{k_{5}} X_{2} + X_{6}$$

$$X_{6} \xrightarrow{k_{6}} X_{5}$$

$$(1)$$

Under mass-action kinetics, we get the following dynamical system

$$\begin{aligned} \frac{dx_1}{dt} &= -k_1 x_1 + k_4 x_3 x_5, & \frac{dx_2}{dt} &= k_1 x_1 - k_2 x_2 + k_5 x_4 x_5, \\ \frac{dx_3}{dt} &= k_2 x_2 - k_3 x_3 - k_4 x_3 x_5, & \frac{dx_4}{dt} &= k_3 x_3 - k_5 x_4 x_5, \\ \frac{dx_5}{dt} &= -k_4 x_3 x_5 - k_5 x_4 x_5 + k_6 x_6, & \frac{dx_6}{dt} &= k_4 x_3 x_5 + k_5 x_4 x_5 - k_6 x_6 \end{aligned}$$

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LINEAR DEPENDENCIES GIVE CONSERVATION RELATIONS From $f_1 + f_2 + f_3 + f_4 = f_5 + f_6 = 0$, we get two conservation relations:

$$x_1 + x_2 + x_3 + x_4 = T_1,$$

$$x_5 + x_6 = T_2.$$

Thus, trajectories lie in a 4d-plane in 6d-space. Total amounts T_1, T_2 are determined by the initial conditions x(0).

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- Starting data: a set of r reactions (labeled edges, e.g. $i \xrightarrow{\kappa_{ij}} j$, where $\kappa_{ij} \in \mathbb{R}_{>0}$ are the reaction rate constants) between mcomplexes (monomials e.g. $x^{y_i} = x_1^{y_{i1}} x_2^{y_{i2}} \cdots x_s^{y_{is}}$) composed of sspecies (variables x_1, \ldots, x_s).
- **Definition:** A chemical reaction network is a finite directed graph $G = (V, E, (\kappa_{ij})_{(i,j) \in E}, (y_i)_{i=1,...,m})$ whose vertices are labeled by complexes and whose edges are labeled by parameters.

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6 reactions (arrows), 10 complexes (nodes), 6 species

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- View the concentrations x_1, x_2, \ldots, x_s as functions of time.
- Mass-action kinetics specified by the network G is the following autonomous system of ordinary differential equations:

$$\frac{dx}{dt} = \sum_{(i,j)\in E} \kappa_{i,j} x^{y_i} (y_j - y_i).$$
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$$\begin{aligned} \frac{dx_1}{dt} &= f_1(x) = -k_1 x_1 + k_4 x_3 x_5, & \frac{dx_2}{dt} = f_2(x) = k_1 x_1 - k_2 x_2 + k_5 x_4 x_5, \\ \frac{dx_3}{dt} &= f_3(x) = k_2 x_2 - k_3 x_3 - k_4 x_3 x_5, & \frac{dx_4}{dt} = f_4(x) = k_3 x_3 - k_5 x_4 x_5, \\ \frac{dx_5}{dt} &= f_5(x) = -k_4 x_3 x_5 - k_5 x_4 x_5 + k_6 x_6, & \frac{dx_6}{dt} = f_6(x) = k_4 x_3 x_5 + k_5 x_4 x_5 - k_6 x_6. \end{aligned}$$

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Proposed by Cato Guldberg (1836–1902) (chemist) and Peter Waage (1833-1900) (mathematician).



Waage was a chemist and Guldberg was a mathematician.

They were close friends and brothers in law. Waage's second wife was Guldberg's sister and they are Ragni Piene's great grandparents! Published in Norwegian in 1862, in French in 1867, and in German around 1880, until it was recognized (in the meantime, it was rediscovered by van't Hoff.)

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$$\frac{dx_k}{dt} = f_k(x), k = 1, \dots, s,$$
(4)

• f_1, \ldots, f_s are polynomials in $\mathbb{R}[x_1, \ldots, x_s]$.

- Linear relations among the vectors $y_j y_i$ give raise to linear conservation relations. Total amounts are determined by the initial conditions.
- By the form of the equations the (closed or open) positive orthant is forward invariant for the dynamics.
- In general, the rate constants $\kappa_{i,j}$ are unknown (difficult or impossible to be determined).

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GENERAL GOAL

Analize mathematical models arising from biochemical reaction networks, formalize and make sense of biologist's intuitions, and make predictions from the structure of the network.



DEFINITION

x^* is a steady state of dx/dt = f(x) if $f(x^*) = 0$.

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A chemical reaction system exhibits multiestationarity if it is possible to find more than one positive steady state in the same stoichiometric compatibility class = with the same total constants.



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$$dx/dt = f(x)$$

The green curve represents the steady states f = 0

The number of intersection points depends on the total constants



USUAL MULTISTATIONARITY PICTURES





More complex:





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USUAL MULTISTATIONARITY PICTURES





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More complex:





- Almost all cells in a body have the same genetic information. Multistationarity in cellular networks can be viewed as a rationale for decision making and cell differentiation [Delbrück'49].
- [Ferrell '09]: Current state of systems biology is like planetary astronomy science before Kepler and Newton and cannot be studied without math and physics.
- Although all biological processes are complex and involve many variables, essential qualitative features of these processes can usually be understood in terms of a small number of crucial variables.
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ANOTHER IMPORTANT PROPERTY

PERSISTENCE

Persistence means that any trajectory starting from a point with positive coordinates stays at a positive distance from any point in the boundary.

So, persistence means that no species which is present can tend to be eliminated in the course of the reaction.

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$$S_{0} + E \stackrel{k_{\text{on}}}{\underset{k_{\text{off}}}{\leftarrow}} ES_{0} \stackrel{k_{\text{cat}}}{\to} S_{1} + E$$
$$S_{1} + F \stackrel{\ell_{\text{on}}}{\underset{\ell_{\text{off}}}{\leftarrow}} FS_{1} \stackrel{\ell_{\text{cat}}}{\to} S_{0} + F$$

E and *F* enzymes, S_0 and S_1 substrates, S_0E and S_1F intermediates and we represent it with: $S_0 \overbrace{F}^E S_1$. There are 6 species 6 complexes (nodes) and 6 reactions (edges)

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Two sequential phosphorylations



WE NUMBER THE SPECIES AND THEIR CONCENTRATIONS

 $x_1, x_2, x_3 =$ concentrations of S_0, S_1, S_2

 $y_1, y_2, y_3, y_4 =$ concentrations of the intermediate species

 $x_4 =$ concentration of the kinase E

 $x_5 =$ concentration of the phosphatase F.

THE DIFFERENTIAL EQUATIONS AND THE CONSERVATION LAWS dx_1

$$\begin{aligned} \frac{dx_1}{dt} &= -k_{\text{on}_0} x_1 x_4 + k_{\text{off}_0} y_1 + l_{\text{cat}_0} y_4 & \frac{dx_4}{dt} = -k_{\text{on}_0} x_1 x_4 - k_{\text{on}_1} x_2 x_4 + (k_{\text{off}_0} + k_{\text{cat}_0}) \\ \frac{dx_2}{dt} &= -k_{\text{on}_1} x_2 x_4 + k_{\text{cat}_0} y_1 + k_{\text{off}_1} y_2 & + (k_{\text{off}_1} + k_{\text{cat}_1}) y_2 \\ -l_{\text{on}_0} x_2 x_5 + l_{\text{cat}_1} y_3 + l_{\text{off}_0} y_4 & \frac{dx_5}{dt} = -l_{\text{on}_0} x_2 x_5 - l_{\text{on}_1} x_3 x_5 + (l_{\text{off}_1} + l_{\text{cat}_1}) y_4 \\ \frac{dx_3}{dt} &= k_{\text{cat}_1} y_2 - l_{\text{on}_1} x_3 x_5 + l_{\text{off}_1} y_3 & + (l_{\text{off}_0} + l_{\text{cat}_0}) y_4 \\ \frac{dy_1}{dt} &= k_{\text{on}_0} x_1 x_4 - (k_{\text{off}_0} + k_{\text{cat}_0}) y_1 & \frac{dy_3}{dt} = l_{\text{on}_1} x_3 x_5 - (l_{\text{off}_1} + l_{\text{cat}_1}) y_3 \\ \frac{dy_2}{dt} &= k_{\text{on}_1} x_2 x_4 - (k_{\text{off}_1} + k_{\text{cat}_1}) y_2 & \frac{dy_4}{dt} = l_{\text{on}_0} x_2 x_5 - (l_{\text{off}_0} + l_{\text{cat}_0}) y_4 \end{aligned}$$

$$\begin{aligned} x_1 + x_2 + x_3 + y_1 + y_2 + y_3 + y_4 = S_{tot} \\ x_4 + y_1 + y_2 = E_{tot} \\ x_5 + y_3 + y_4 = F_{tot}. \end{aligned}$$

OTHER IMPORTANT EXAMPLES OF NETWORKS

Phosphorylation cascades



OTHER IMPORTANT EXAMPLES OF NETWORKS

Phosphorylation cascades with retroactivity



OTHER IMPORTANT EXAMPLES OF NETWORKS Different phosphatases vs same phosphatase in a cascade





ALICIA DICKENSTEIN (UBA)

EXAMPLE: PROCESSIVE PHOSPHORILATIONS

$$S_0 + K \xrightarrow[k_2]{k_1} S_0 K \xrightarrow[k_4]{k_4} S_1 K \xrightarrow[k_6]{k_5} \dots \xrightarrow[k_{2n-1}]{k_{2n}} S_{n-1} K \xrightarrow[k_{2n+1}]{k_{2n+1}} S_n + K$$
$$S_n + F \xrightarrow[\ell_{2n+1}]{\ell_{2n}} S_n F \xrightarrow[\ell_{2n-2}]{\ell_{2n-2}} \dots \xrightarrow[\ell_5]{\ell_5} S_2 F \xrightarrow[\ell_6]{\ell_2} S_1 F \xrightarrow[\ell_1]{\ell_1} S_0 + F$$

C. CONRADI AND A. SHIU. A global convergence result for processive multisite phosphorylation

systems, 2015.

SMALL MOTIFS ([ALON'07, FELIU-WIUF'12])



SHVARTSMAN'S ENZYMATIC NETWORK



A COMMON STRUCTURE (ARXIV:1612.08763)

MESSI Systems

We identified with Mercedes Pérez Millán a **common structure** in many popular biological networks that describe Modifications of type Enzyme-Substrate or Swap with Intermediates, which allows us to prove general results valid in all these networks. MESSI systems

include **all** the previous ones.

Less general, but stil quite general goal

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A MESSI network is a chemical reaction network satisfying the following properties. When endowed with mass-action kinetics, we have a MESSI system.

• There exists a **partition** of the set S of species:



- There are two types of complexes: intermediates

 (consisting of a single intermediate species) and
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Examples: All the examples we mentioned ... plus many other common biochemical models.

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Enzymes and swaps

- In a reaction $X_i + X_\ell \to X_j + X_\ell$, we say that X_ℓ acts as an enzyme.
- A reaction $X_i + X_\ell \to X_j + X_m$, with i, ℓ, j, m distinct, is called a swap.
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Conserved quantities: Theorem 1 [D.-P. M.]

A MESSI system has one (independent) linear conservation relation associated to each of the subsets $S^{(\alpha)}, 1 \leq \alpha \leq M$, in the partition of the species set corresponding to non-intermediate species:

$$\sum_{\mathbf{X}_i \in \mathcal{S}^{(\alpha)}} x_i + \sum_{\mathbf{X}_k \in \text{Int}_{\alpha}} x_k = \text{ constant},$$

where $\operatorname{Int}_{\alpha} = \{ \mathbf{X}_{\mathbf{k}} : X_i \to_{\circ} \mathbf{X}_{\mathbf{k}} \text{ or } X_i + X_j \to_{\circ} \mathbf{X}_{\mathbf{k}} \text{ for some } X_i \in \mathcal{S}^{(\alpha)} \}.$

OBSERVATION:

- Theorem 1 implies that all MESSI systems are conservative (and thus the solutions are defined for any positive time).
- Question: when these span all the linear conservation laws?
- We give different sufficient restrictive conditions, satisfied by most common biochemical enzymatic models. We show counterexamples if any of these conditions is released

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From G to G_1 (without intermediates)

Going from G to G_1 we delete intermediates and we put an edge between two core complexes $y_i \to y_j$ if $y_1 \to y_j$ in G:



FIGURE: $S^{(0)} \subseteq \{Z_1, Z_2, Z_3\}, S^{(1)} = \{y_1, y_2, y_3\}$

In all cases G = A, B, C, D (with rate constants κ), the associated digraph G_1 is A.

Wiuf and Feliu proved that with rate constants $\tau(\kappa)$ and QSSA style substitutions, G_1 has still mass-action kinetics.

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MESSI SYSTEMS

 $G_1 \rightarrow G_2$ (hide enzymes and swaps in labels)

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PRECLUDING RELEVANT BOUNDARY STEADY STATES

If we have a minimal partition, we define a new graph G_E , whose vertices are the sets $S^{(\alpha)}$ for $\alpha \geq 1$, and there is an edge from $S^{(\alpha)}$ to $S^{(\beta)}$ if there is a species in $S^{(\alpha)}$ on a label of an edge in G_2 between species of $S^{(\beta)}$.

Persistence: Theorem 2 [D.-P. M.]

If there is no directed cycle in G_E , then G has no boundary steady states in any positive stoichiometric compatibility class. Thus, the network is persistent.

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EXAMPLES

$$\begin{array}{c|c} E\\ S_{0} & S_{1}\\ F & P_{0} & P_{1}\\ F\\ S^{(1)} &= \{S_{0}, S_{1}\},\\ S^{(2)} &= \{P_{0}, P_{1}\},\\ S^{(3)} &= \{E\}, S^{(4)} = \{F\}. \end{array} \qquad \begin{array}{c|c} G_{2}:\\ S_{0} & \stackrel{\tau_{1}e}{\rightleftharpoons} S_{1}\\ \tau_{2}f & S_{1}\\ T_{2}f & S_{1} & S^{(3)} \rightarrow S^{(1)} \rightarrow S^{(2)}\\ P_{0} & \stackrel{\tau_{3}s_{1}}{\nleftrightarrow} P_{1}\\ \tau_{4}f & Persistent \end{array} \qquad \begin{array}{c|c} S^{(4)} & \xrightarrow{F} S^{(2)}\\ Persistent & S^{(1)} &= S^{(2)}\\ S^{(1)} &= \{X, XT, X_{p}\}, S^{(2)} = \\ \{Y, Y_{p}\}. \end{array} \qquad \begin{array}{c|c} G_{E}:\\ S^{(1)} &\equiv S^{(2)}\\ x_{p} &= X_{tot}, y_{p} &= Y_{tot}, x &= x_{t} &= x_{p}y &= \\ x_{T}y_{p} &= y &= 0 & \text{is a boundary steady}\\ \text{state in the class with totals } X_{tot}, Y_{tot} \end{array}$$

EXAMPLES

- There is at most a single positive solution in $V \cap x(0) + S$ for any x(0) in the positive orthant (monostationarity), for any choice of rate constants κ .
- **2** For all subsets $J \subseteq [s]$ of cardinality d, the product $\det(S_J^{\perp}) \det(A_J)$ either is zero or has the same sign as all other nonzero products, and at least one such product is nonzero.
- **3** Same sign conditions with $det(S_J) det(B_J)$.
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- Theorem 3 is based on several previous papers, including joint papers in [FOCM 2016, Bull. Math. Biol. 2012], which in turn generalized several papers starting with Craciun-Feinberg, SIAP, 2005-06.
- We give precise sufficient conditions for the hypotheses of Theorem 3 to hold.
- We implemented Theorem 3 to decide if a network has the capacity for multistationarity.
- Once this is the case, we give an algorithm to produce vectors of rate constants k for which multistationarity occurs. This is based in the theory of oriented matroids, that goes back to Rockafellar.
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JOINT WORK WITH F. BIHAN AND M. GIAROLI

REGIONS OF MULTISTATIONARITY

We devised a method to give open regions in rate constant + total amount space where multistationarity occurs for all k, T in these regions. This is based on a result by Bihan, Santos and Spaenlehauer in real algebraic geometry (arXiv:2018) which uses regular triangulations of the convex hull of the exponents occuring in f_1, \ldots, f_n .



Coming back to the two-component system

$$X_{1} \xrightarrow{k_{1}} X_{2} \xrightarrow{k_{2}} X_{3} \xrightarrow{k_{3}} X_{4}$$

$$X_{3} + X_{5} \xrightarrow{k_{4}} X_{1} + X_{6}$$

$$X_{4} + X_{5} \xrightarrow{k_{5}} X_{2} + X_{6}$$

$$X_{6} \xrightarrow{k_{6}} X_{5}$$

$$(5)$$

$$x_1 + x_2 + x_3 + x_4 = T_1,$$

$$x_5 + x_6 = T_2.$$

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OUR RESULTS FOR THE TWO-COMPONENT SYSTEM

Multstationarity parameters: Theorem 4 [B.-D.-G.]

With the previous notations, assume that the reaction rate constants and the total amounts verify the inequalities

$$k_6\left(\frac{1}{k_2} + \frac{1}{k_3}\right) < \frac{T_1}{T_2} < k_6\left(\frac{1}{k_1} + \frac{1}{k_2}\right)$$

Then, there exist positive constants N_1, N_2 such that for any values of γ_4 and γ_5 veryfying $\gamma_4 > N_1$ and $\frac{\gamma_5}{\gamma_4} > N_2$, the rescaling of the given parameters k_4, k_5 by $\overline{k_4} = \gamma_4 k_4$, $\overline{k_5} = \gamma_5 k_5$, gives raise to a multistationary system.

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OTHER APPROACHES TO MULTISTATIONARITY

- Using degree theory (Brouwer's theorem): Conradi-Feliu-Mincheva-Wiuf, PLOS Computational Biology 2017.
- Using numerical or symbolic methods to detect points in different chambers of the complement of the discriminant: Harrington-Mehta-Byrne-Hauenstein 2016; Gross-Harrington-Rosen-Sturmfels, BMB 2016; Faugère-Moroz-Rouillier-Safey El Din, ISSAC 2008 and other.
- Several authors: direct computations of small subnetworks + extrapolation: Conradi et al. 2007 and other, Joshi-Shiu 2013 and 2017, Banaji-Pantea 2016 and 2017.
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- ... and (in some interesting cases) to "see the woods"

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CONCLUSIONS

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